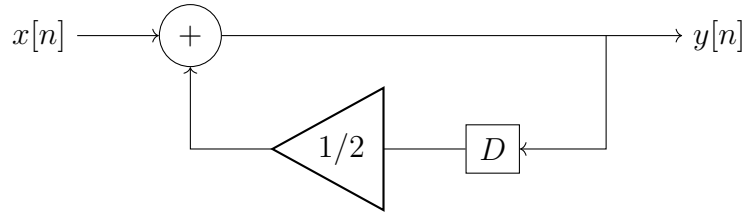


Problem 1: Frequency Response from a DAG Block Diagram

Consider a DT LTI system with input $x[n]$ and output $y[n]$ that is implemented by the following block diagram:



- (a) Find the LCCDE that describes this system.

- (b) Find the frequency response $H(\omega)$ of this system.

- (c) Find the impulse response $h[n]$ of the system. Assume that $h[n] = 0$ for $n < 0$.

Problem 2: Magnitude Response

You are given an LTI system described by the following equation:

$$y(n) = \frac{1}{4}x[n] - \frac{1}{4}x[n-1].$$

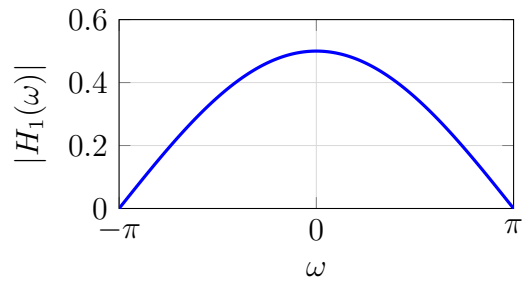
- (a) For the system given above, find both the impulse response and the frequency response.

- (b) What is the magnitude of the frequency response? Match the frequency response's magnitude to the two correct plots below.

Is this a high-pass or low-pass filter?

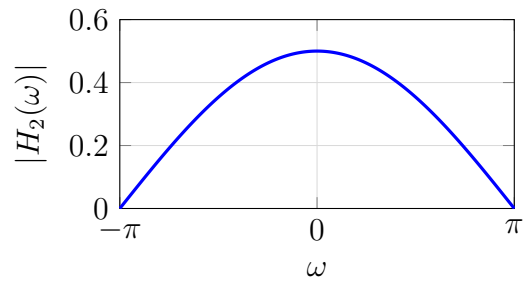
(1)

Magnitude Response of $H_1(\omega)$



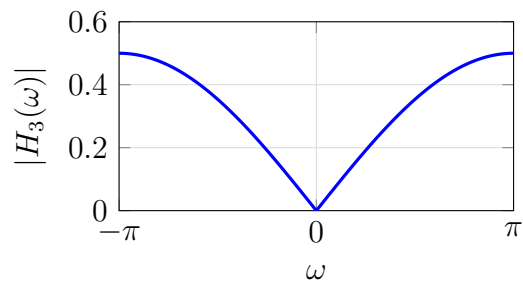
(2)

Magnitude Response of $H_2(\omega)$



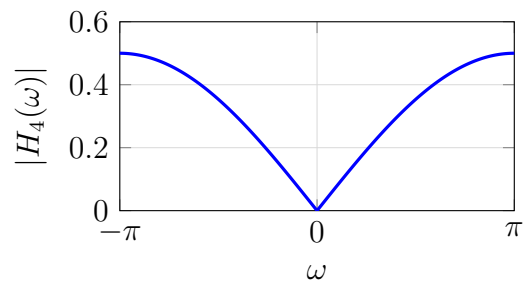
(3)

Magnitude Response of $H_3(\omega)$



(4)

Magnitude Response of $H_4(\omega)$



Problem 3: Making LTI more LIT.

Consider a causal LTI system with frequency response:

$$H(\omega) = \frac{1 + \frac{3}{2}e^{-i\omega}}{1 - \frac{1}{2}e^{-i\omega}}$$

- (a) Write a difference equation relating $x[n]$ and $y[n]$ for this system.
- (b) Draw a block diagram implementing this system with only one delay block.
- (c) Determine the impulse response $h[n]$.